

A COMPARISON AMONG SOME SAMPLING STRATEGIES UNDER A MODEL

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1. INTRODUCTION

Various results are well-known in the literature [vide Durbin (7), Rao (14), Rao and Webster (16), Rao and Ramchandran (17), Rao (18), Rao and Rao (19), Singh (21) and Chakrabarti (2) among others] concerning the relative efficiencies, under various circumstances, of several sampling strategies for estimating a finite population mean $\bar{Y} = 1/N \sum y_i$ for a variate y for which the value y_i on the i th unit of the population satisfies the following general model :

$$y_i = \alpha + \beta x_i + u_i \quad (i=1, \dots, N), \quad \dots(1.1)$$

where u_i 's are random variables with conditional expectations

$$e(u_i/x_i) = 0,$$

$$e(u_i^2/x_i) = \delta x_i, \quad g \forall i$$

$$(\delta > 0, g = \text{a real number}),$$

$$e(u_i u_j/x_i, x_j) = 0 \quad \forall i, j \quad (i \neq j),$$

x_i 's are known real quantities which are either fixed (non-stochastic) constants or realizations on random variates usually with incompletely specified distributions. In this paper our modest purpose is to compare the relative efficiencies of a few customary sampling strategies under a rather simplistic special case of the above model [say, Model I, assumed, essentially following Chakrabarti (2), but stretching his ideas a little] for which $g=0$ and x_i s are identically and independently gamma-distributed with a mean parameter m taken equal to [may not be too disconcerting if one assumes, as we do, N to be large, in view of the Central Limit Theorem] the known value $\bar{X} = 1/N \sum x_i$. The

results (which are exact and valid for any sample-size) we derive in the sequel seem to be interesting and point to the appropriateness of a particular one among the sampling strategies we study under various circumstances. These, of course, do not follow as corollaries from results already available in the literature under more general models with $g \neq 0$ and x_i s having different and incompletely specified distributions. Obviously, our results are subject to severe limitations in respect of the nature of the y -variate-values to which they apply. Yet we present them because the model I we postulate is already receiving attention in the literature and we believe it is worthwhile to note a few of its implications on the relative efficiencies of several popular sampling strategies. We are, however, as yet unable to report more interesting results which should apply to situations with incompletely specified gamma distributions for x_i s and with the stipulation $g=0$ relaxed, but research along the line indicated is in progress.

In the end we present a few asymptotic results concerning the relative efficiencies of the same sampling strategies under an extended model (to be called Model II) following Singh's (21) works, on dispensing with the assumption about the gamma form of the distributions of x_i s.

In this note we shall denote a sample (typically, of size n as treated throughout) by s , its selection-probability by $p(s)$ for a design p (generically), and the expectation-operator (for the design) by E . Also, we shall use ϵ for expectation over u (with fixed \bar{x}), ϵ_x for expectation over the distribution of x , $\bar{\epsilon} = \epsilon_x \epsilon$ for the two-step expectation (for u with fixed x and then over x) and $e = \bar{\epsilon} E = \epsilon_x \epsilon E$ to denote the three-step (including the one over the sampling-design p) expectation-operator.

Here we study only six strategies consecutively numbered as 1, ..., 6 which respectively involve the estimators $t_1 = \bar{X} \frac{\bar{y}}{\bar{x}}$ (\bar{y} , \bar{x} being the same means), $t_2 = \bar{X} \frac{1}{n} \sum_s \frac{y_i}{x_i}$, both based on the SRSWOR scheme, $t_3 = t_1$ based on Midzuno-Sen-Lahiri (11) scheme, the Horvitz-Thompson (10) estimator $t_4 = 1/N \sum_s y_i/\pi_i$ based on a πps design with inclusion-probability $\pi_i = n \frac{x_i}{N\bar{x}} = np_i \forall_i$ (say), and t_5 , t_6 , the usual Rao-Hartley-Cochran (RHC. in brief) (15) and Hansen-Hurwitz

estimators (HHE, in brief) (8) involving normed size-measures p_i s. The expectations, biases and mean-square-errors of the estimators will be denoted respectively as

$$E(t_i), \epsilon_i = e(t_i) = \bar{e} E(t_i) = \epsilon_x \epsilon E(t_i) = \epsilon_x E \epsilon(t_i),$$

$$B_i = B(t_i) = e.(t_i - \bar{Y}) = \bar{e} [E(t_i) - \bar{Y}] = \epsilon_x [\epsilon (E(t_i) - \bar{Y})]$$

and $M_i = \bar{e} [E(t_i - \bar{Y})^2] = \epsilon_x [\epsilon \{E(t_i - \bar{Y})^2\}]$

(in case $\alpha=0$ in the model (1.1), we shall write M_i' for M_i), $i=1, \dots, 6$.

2. NEW AND EXACT (SMALL-SAMPLE) RESULTS CONCERNING RELATIVE EFFICIENCIES OF SAMPLING STRATEGIES UNDER MODEL I AND RELATED EARLIER RESULTS UNDER ALTERNATIVE MODELS

Utilizing the properties of a gamma distribution with density $f(x) = 1/\Gamma(m) e^{-x} x^{m-1}$, $x > 0$, $m > 0$, with parameter m , we get, after some algebraic manipulations whenever needed :

$$\epsilon_1 = \alpha \frac{nm}{nm-1} + \beta m,$$

$$B_1 = \alpha \left(\frac{1}{nm-1} \right)$$

$$M_1 = \alpha^2 \frac{nm+2}{(nm-1)(nm-2)} + \frac{\delta nm^2}{(nm-1)(nm-2)} - \frac{\delta}{N} \frac{nm+1}{nm-1}$$

$$\epsilon_2 = \frac{\alpha m}{m-1} + \beta m,$$

$$B_2 = \alpha (1/m-1)$$

$$M_2 = \alpha^2 \left[\frac{m^2}{n} \frac{1}{(m-1)(m-2)} + \frac{n-1}{(m-1)^2} + 1 - \frac{2m}{m-1} \right] + \frac{\delta}{n} \frac{m^2}{(m-1)(m-2)} - \frac{2m}{N} \frac{\delta}{(m-1)} + \frac{\delta}{N},$$

$$\epsilon_3 = \epsilon_4 = \epsilon_5 = \epsilon_6 = \alpha + \beta m,$$

$$M_3 = \frac{\alpha^2}{(nm-1)} + \delta \frac{m}{(nm-1)} - \frac{\delta}{N},$$

$$M_4 = \frac{m}{(m-1)} \frac{\delta}{n} - \frac{\delta}{N}$$

(M_4 is complicated and hence not included)

$$M_5 = \frac{N-1}{N-n} \frac{1}{n} \left(\frac{\alpha^2}{m-1} + \delta \frac{m}{m-1} - \frac{\delta}{N} \right),$$

$$M_6 = \frac{N-1}{N-n} M_5.$$

The expression for M_2 is complicated. So, it is difficult to compare it with other M_i s. However, if m is so large that we may neglect the error in writing $\frac{1}{m-2}$ for $\frac{1}{m-1}$ neglecting terms $O(1/m^2)$ then an approximate expression for it written \bar{M} turns out to be

$$\bar{M}_2 = \alpha^2 \frac{m+2}{(m-1)(m-2)} + \frac{\delta}{n} \frac{m^2}{(m-1)(m-2)} - \frac{\delta}{n} \frac{m+1}{m-1}$$

(in case $\alpha=0$, we shall write \bar{M}_2 for \bar{M}_2).

We shall use M_2 (and M_2') to compare the efficiency of the strategy 2 with others. As this approximation is introduced for the sake of sheer simplicity alone we shall not make the corresponding approximations to other M_i 's while comparing them.

The relative efficiencies of the strategies under Model I turn out, suppressing the algebraic steps, as follows :

$\bar{M}_2' > M_1'$, if $m > 2$ (a condition we assume throughout to be true) ;

$$\bar{M}_2 > M_1 \text{ if } m \geq 4; |B_2| > |B_1|; M_1 > M_3; \bar{M}_2 > M_3;$$

$$M_1' < M_4' \forall n \geq 3; \bar{M}_2' > M_4';$$

$$M_3' < M_4'; M_1' < M_5' \text{ if } n > 2; M_1 < M_6 \text{ if } n \geq 5; M_3' < M_5';$$

$$M_3 < M_6; M_5' < M_4'.$$

Remark I. Under the Model I the unbiased ratio-estimator based on Ikeda-Sen-Midzuno-Lahiri (11) scheme fares best among its competitors considered here.

The Model I with the assumption in particular that $m = \bar{X}$, renders peculiarities to the relative efficiencies of the strategies. For some other models studied in the literature their standings are not quite alike and some of the relevant results are noted below.

Taking $\alpha=0$ and $0 \leq g \leq 2$ and without assuming a particular form for the distribution of x_{is} , Rao (13) found, inter alia, that

$$M_3' < M_6' \text{ if } g \leq 1; M_4' < M_6' \forall g; M_3' \geq M_4' \text{ according}$$

$$\text{as } g \geq 1;$$

$M_5' \geq M_4' \text{ if } g \geq 1; M_3' \geq M_5' \text{ according as } g \geq 1, \text{ only if } n$
is large ;

$M_3' = M_4' = M_5'$ if $g=1$; $M_4' < M_5'$, $M_4' < M_3'$ if $1 < g < 2$ and if N is large and $\text{Max } p_i$ is 0 ($1/N$) $\forall i$; $M_4' < M_5'$, $M_4' < M_3'$ if $g=2$.

For the same model Raj (12) showed earlier that $M_3' < M_6'$ if $n=2$ and $g=0$ or $g=1$. Hanurav (9) and Rao (20) showed respectively that $M_4' \leq M_5'$ and $M_4' \leq M_3'$ according as $g \geq 1$. Chaudhuri (4) showed that $M_1' > M_4'$ if $g \geq 1$ and Chaudhuri and Arnab (5) have shown that $M_4' \leq M_5' \leq M_3'$ according as $g \geq 1$.

Rao (18), on the other hand, assumed a model different from I only in relaxing the restriction that $m = \bar{X}$ and observed the following:

$M_3 < M_1$ if $0 \leq g \leq 2$; $M_3 < M_5$ if $0 \leq g \leq 1$; $M_1 < M_5$ if $g=0, n > 4$; $M_3' < M_1'$ if $0 \leq g \leq 2$; $M_5' > M_3'$ if $0 \leq g \leq 1$; $M_3' \leq M_5'$ if $g=1$; $M_5' < M_3'$ if $1 < g \leq 2$; $M_1' < M_5'$ if $g=0, n > 2$; $M_5' < M_1'$ if $1 \leq g \leq 2$.

It is interesting to note the difference caused by taking $m = \bar{X}$ in the model.

3. A FEW ASYMPTOTIC RESULTS

In a recent article Singh (21) compared the strategies 1 and 3 by considering asymptotic expressions for the mean square errors of t_1 and t_3 and also on assuming in addition normality of the joint distribution of x_i and y_i for $i=1, \dots, N$ and also under some other assumptions. Here we consider similar asymptotic expressions for these mean square errors assuming Chakrabarti's (2) model with the relaxation that x_i s are identically and independently distributed with a mean $m = \bar{X}$ (known), the common distribution being not necessarily of the gamma form the resulting generalized model being denoted as II. Naturally, the (asymptotic) expressions for the mean square errors do not agree with those due to Singh (21) because of the simplification we achieve by virtue of the assumption that m equals \bar{X} which is a fixed known quantity but we still have positive conclusions concerning their relative magnitudes as shown below.

Let us write $\bar{y} = \bar{Y} + \xi,$

$$\bar{x} = \bar{X} - \eta,$$

$$\bar{u} = \frac{1}{n} \sum_s u_i,$$

$$\bar{U} = 1/N \sum_1^N u_i,$$

$$R = \bar{Y}/\bar{X} = \bar{Y}/m = \beta + \frac{a + \bar{U}}{m}.$$

5. NUMERICAL VALUES OF RELATIVE EFFICIENCIES OF STRATEGIES

Defining the efficiencies of the strategies as $E_i = 100 \bar{M}_2 / M_i$ (or as $E_i = 100 \bar{M}'_2 / M'_i$ in case $\alpha = 0$), $i = 1, \dots, 6$, we present below the values of the relative efficiencies of the strategies for a few combinations of the parametric values.

Parametric combination		Efficiencies of the strategies					
		E_1	E_2	E_3	E_4	E_5	E_6
I	$\alpha = 0.5, \beta = 1.0$ $\delta = 2.0, m = 5$ $\eta = 6, N = 20$	256	100	276	—	246	168
II	$\alpha = 1.5, \beta = 0.5$ $\delta = 2.0, m = 8$ $n = 4, N = 40$	212	100	228	—	208	192
III	$\alpha = 0, \beta = 1.5$ $\eta = 2.5, m = 6$ $n = 5, N = 10$	189	100	204	157	177	100

Thus, in each $E_3 > E_1 > E_5 > E_6 \geq E_2$; our theoretical findings in favour of strategy 3 corroborated.

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SUMMARY

In estimating a finite population mean, we investigate the "small sample" relative efficiencies of several well-known sampling strategies under Chakrabarti's (2) model and find the one due to Ikeda-Sen-Midzuno-Lahiri (11) to be the most promising among them. A similar conclusion is reached with a slight generalization of the model coupled with large sample approximations.

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