

Improved Ratio-type Estimator for Variance Using Auxiliary Information

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SUMMARY

For estimating the population variance using information on several auxiliary variables, an improved ratio-type estimator is defined. It is shown that proposed estimator is more efficient than the usual unbiased estimator and the Isaki [5] estimator. Double sampling version of the suggested estimator is also discussed.

Key words : Ratio-type estimator, Multi-auxiliary information, Multivariate normal population.

1. Introduction

Suppose we have a population of N identifiable units on which $(k + 1)$ characteristics y, x_1, x_2, \dots, x_k are defined. Here y is the characteristic of interest and $x_i, (i = 1, 2, \dots, k)$ are auxiliary characteristics whose population variances $\sigma_i^2, (i = 1, 2, \dots, k)$ are assumed to be known. Let (y_h, x_{ih}) denote the values of y and x_i on the unit h . Assume that a simple random sample of size n is drawn with replacement, $(y_h, x_{ih}), (h = 1, 2, \dots, n)$ are observed. Now assume that the problem is to estimate the population variance

$$S_y^2 = \left(\frac{1}{N} \right) \sum_{h=1}^N (y_h - \bar{Y})^2 = \theta \sum_{h \neq j}^N (y_h - y_j)^2, \theta = [N(N-1)]^{-1}$$
$$\bar{Y} = \left(\frac{1}{N} \right) \sum_{h=1}^N y_h$$

when S_x^2 , the population variance of auxiliary character x is known, Isaki [5] considered the problem of estimating S_y^2 and suggested univariate, multivariate ratio and regression estimators with their properties. In this paper, we have proposed a multivariate ratio-type estimator for population variance of y and its properties are discussed in single phase as well as in two phase sampling.

Let $z = (y, x)$ denote a $1 \times (k + 1)$ vector where the population variances of each component of the vector x are assumed to be known. Let

$$\mu = (\mu_0, \mu_1, \mu_2, \dots, \mu_k)' \text{ and } \Omega = (\sigma_{ij})$$

denote the mean and covariance of z where

$$\left. \begin{aligned} \sigma_{ij} &= \sigma_i^2 && \text{if } i = j, (i, j) = 0, 1, 2, \dots, k \\ &= \rho_{ij} \sigma_i \sigma_j && \text{otherwise} \end{aligned} \right\} \tag{1.1}$$

In particular $\rho_{ij} = \rho, (i, j) = 0, 1, 2, \dots, k$ the model (1.1) reduces to

$$\left. \begin{aligned} \sigma_{ij} &= \sigma_i^2 && \text{if } i = j, (i, j) = 0, 1, 2, \dots, k \\ &= \rho \sigma_i \sigma_j && \text{otherwise} \end{aligned} \right\} \tag{1.2}$$

and $-k^{-1} < \rho < 1$. Assume that z possesses the same moments as a $1 \times (k + 1)$ multivariate normal variable up to the fourth order. Let

$$s_{ij} = (n - 1)^{-1} \sum_{h=1}^n (z_{ih} - \bar{z}_i) z_{jh}, i, j = 0, 1, 2, \dots, k \tag{1.3}$$

Then, following Olkin [10], Isaki [5] constructed the multivariate ratio estimator for σ_0^2 as

$$\hat{S}_{ym1}^2 = \sum_{i=1}^k w_i \hat{r}_i \sigma_i^2 \tag{1.4}$$

where $\hat{r}_i = s_{ii}^{-1} s_{00} = \left(\frac{s_0^2}{s_i^2} \right), i = 1, 2, \dots, k; 0 < w_i < 1; \sum_{i=1}^k w_i = 1$ and it is assumed that the $\sigma_i^2, i = 1, 2, \dots, k;$ are known while ρ and σ_0^2 are unknown.

Motivated by Shukla [14] and John [6] and Mohanty and Pattanaik [8], one may define the following alternative multivariate ratio-type estimators for σ_0^2 as

$$\hat{S}_{ym2}^2 = s_0^2 \left[\frac{\left(\sum_{i=1}^k w_i \sigma_i^2 \right)}{\left(\sum_{i=1}^k w_i s_i^2 \right)} \right] \tag{1.5}$$

$$\hat{S}_{ym3}^2 = \prod_{i=1}^k (\hat{f}_i \sigma_i^2) w_i \tag{1.6}$$

and

$$\hat{S}_{ym4}^2 = \left(\sum_{i=1}^k \frac{w_i}{\hat{f}_i \sigma_i^2} \right)^{-1} \tag{1.7}$$

where w_i 's ($i = 1, 2, \dots, k$) are the weights such that $\sum_{i=1}^k w_i = 1$.

We note from Agrawal and Panda [1] that with $w'_i = \frac{\left(w_i \prod_{j \neq i}^k \sigma_j^2 \right)}{\sum_{i=1}^k \left(w_i \prod_{j \neq i}^k \sigma_j^2 \right)}$ and

$\sum_{i=1}^k w'_i = 1$, the estimator S_{ym4}^2 takes the form

$$\hat{S}_{ym4}^{\prime 2} = s_0^2 \left[\frac{\left(\sum_{i=1}^k w'_i \sigma_i^2 \right)}{\left(\sum_{i=1}^k w'_i s_i^2 \right)} \right]$$

which is similar to Shukla [14] and John [6] type estimator \hat{S}_{ym2}^2 .

Under the set up (1.2) the common minimum variance of the estimators \hat{S}_{ymj}^2 ($j = 1$ to 4) to the first degree of approximation is given by

$$\min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{ymj}^2) = [k(n-1)]^{-1} [2(k+1)(1-\rho^2)\sigma_0^4] \tag{1.8}$$

With the assumption that z possesses the same moments as in the above, the variance of s_0^2 is

$$\text{Var}(s_0^2) = (n-1)^{-1} 2\sigma_0^4 \tag{1.9}$$

If follows from (1.8) and (1.9) that

$$\min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{ymj}^2) \leq \text{Var}(s_0^2) \text{ iff } |\rho| \geq (k+1)^{-1/2} \tag{1.10}$$

The other relevant references related with the present investigation are Das and Tripathi [4], Srivastava and Jhaggi [16], Prasad and Singh ([11] and [12]), Biradar and Singh [3], Singh *et al.* [15], Sthapit [17], Arcos Ceberian and Rueda Gracia [2], Rueda Gracia and Arcos Ceberain [13] and Upadhyaya and Singh [20] etc.

2. The Suggested Estimator and its Variance

We suggest the estimator for σ_0^2 as

$$\hat{S}_{ym}^{*2} = \sum_{i=1}^k w_i \hat{t}_i \sigma_i^2 + w_{k+1} s_0^2 \tag{2.1}$$

where $\theta < w_i < 1, \sum_{i=1}^{k+1} w_i = 1$

It is noticed from (2.1) that \hat{S}_{ym}^{*2} reduces to the usual unbiased estimator s_0^2 if $w_i = 0$ for $i = 1, 2, \dots, k$ and it reduces to Isaki [5] estimator \hat{S}_{ym1}^2 for $w_{k+1} = 0$. Under the set up (1.1) the variance of \hat{S}_{ym}^{*2} to the first degree of approximation is given by

$$\text{Var}(\hat{S}_{ym}^{*2}) = \left(\frac{2\sigma_0^4}{n-1} \right) [1 - 2 \underline{d}' \underline{w} + \underline{w}' \underline{D} \underline{w}] \tag{2.2}$$

where $\underline{D} = \begin{bmatrix} 1 & \rho_{12}^2 & \dots & \rho_{1(k-1)}^2 & \rho_{1k}^2 \\ \rho_{21}^2 & 1 & \dots & \rho_{2(k-1)}^2 & \rho_{2k}^2 \\ \dots & \dots & \dots & \dots & \dots \\ \rho_{(k-1)1}^2 & \rho_{(k-1)2}^2 & \dots & 1 & \rho_{(k-1)k}^2 \\ \rho_{k1}^2 & \rho_{k2}^2 & \dots & \rho_{k(k-1)}^2 & 1 \end{bmatrix}_{k \times k}$ and

$$\underline{d}' = [\rho_{01}^2 \ \rho_{02}^2 \ \rho_{03}^2 \ \dots \ \rho_{0k}^2]_{1 \times k}$$

Minimization of (2.2) yields

$$\underline{w} = \underline{D}^{-1} \underline{d} \text{ and } w_{k+1} = (1 - \underline{D}^{-1} \underline{d}) \tag{2.3}$$

Substitution of (2.3) in (2.2) gives the minimum variance of \hat{S}_{ym}^{*2} as

$$\min. \text{Var} (\hat{S}_{ym}^{*2}) = \frac{2\sigma_0^4}{(n-1)} (1 - \underline{d}' \underline{D} \underline{d}) \quad (2.4)$$

which is smaller than that of the usual unbiased estimator s_0^2 .

Under the set up (1.2), the variance of \hat{S}_{ym}^{*2} to the first degree of approximation is given by

$$\text{Var} (\hat{S}_{ym}^{*2}) = \left(\frac{2\sigma_0^4}{n-1} \right) [1 - 2 \underline{d}' \underline{w} + \underline{w}' \underline{D}^* \underline{w}] \quad (2.5)$$

which is minimized for

$$\underline{w} = \underline{D}^{*-1} \underline{d}^* \text{ and } w_{k+1} = (1 - \underline{D}^{*-1} \underline{d}^*) \quad (2.6)$$

with

$$\underline{d}^* = \begin{bmatrix} \rho^2 \\ \rho^2 \\ \rho^2 \\ \vdots \\ \rho^2 \end{bmatrix}_{k \times 1} \quad \text{and } \underline{D}^* = \begin{bmatrix} 1 & \rho^2 & \dots & \rho^2 \\ \rho^2 & 1 & \dots & \rho^2 \\ \dots & \dots & \dots & \dots \\ \rho^2 & \rho^2 & \dots & \rho^2 \\ \rho^2 & \rho^2 & \dots & 1 \end{bmatrix}_{k \times k}$$

Substitution of (2.6) in (2.5) yields the minimum variance of \hat{S}_{ym}^{*2} is given by

$$\begin{aligned} \min. \text{Var} (\hat{S}_{ym}^{*2}) &= \frac{2\sigma_0^4}{(n-1)} (1 - \underline{d}' \underline{D}^* \underline{d}^*) \\ &= \frac{2\sigma_0^4}{(n-1)} \left[1 - \frac{k\rho^4}{(1 + (k-1)\rho^2)} \right] \end{aligned} \quad (2.7)$$

Thus to a first order of approximation, the estimator \hat{S}_{ym}^{*2} is as efficient as a multivariate regression estimator. We mention in passing that the optimal choice of the weights w_i involves population quantity (ρ) which is unknown. However, this can be either assessed quite accurately from the past experience or estimated in a reasonable way from the sample at hand, for instance, see Murthy [9] and Tankou and Dharmadhikari [19].

We have from (1.10) and (2.7) that

$$\min.\text{Var}(\hat{S}_{ym}^{*2}) - \min_{j=1 \text{ to } 4}.\text{Var}(\hat{S}_{mj}^{*2}) = \frac{2\sigma_0^4}{(n-1)} \frac{(1-\rho^2)^2}{k\{1+(k-1)\rho^2\}} \geq 0 \quad (2.8)$$

which implies that

$$\min.\text{Var}(\hat{S}_{ym}^{*2}) \leq \min.\text{Var}(\hat{S}_{ym}^2) \quad (2.9)$$

It follows from (1.12) and (2.9) that

$$\min.\text{Var}(\hat{S}_{ym}^{*2}) \leq \min_{j=1 \text{ to } 4}.\text{Var}(\hat{S}_{ymj}^2) \leq \text{Var}(s_0^2) \text{ iff } |\rho| \geq (k+1)^{-1/2} \quad (2.10)$$

Further, we have from (1.11) and (2.7) that

$$\text{Var}(s_0^2) - \min.\text{Var}(\hat{S}_{ym}^{*2}) = \frac{2\sigma_0^4}{(n-1)} \frac{k\rho^4}{[1+(k-1)\rho^2]} \geq 0 \quad (2.11)$$

Thus it follows from (2.8) and (2.11) that the suggested estimator \hat{S}_{ym}^* is more efficient than the usual unbiased estimator s_0^2 and Isaki [5] estimator \hat{S}_{ym1}^2 .

3. Two Phase Sampling

If the required auxiliary information is not readily available for the population before sampling, it might pay to collect such information for a large preliminary sample and then collect more precise information for the variable of interest on a second phase sample. This procedure is known as two phase sampling (or double sampling), is very much use in the practice. The second phase sample may be either (i) a subsample of the large first-phase sample (designated as Case I) or (ii) it may be selected independently (designated as Case II).

Let the first and second phase sample sizes be n_1 and n respectively and

$$s_{ij}^* = (n_1 - 1)^{-1} \sum_{h=1}^{n_1} (z_{ih} - \bar{z}_i) z_{jh}$$

and
$$s_{ij} = (n - 1)^{-1} \sum_{h=1}^n (z_{ih} - \bar{z}_i) z_{jh}, \quad (i, j) = 0, 1, 2, \dots, k$$

represents the corresponding covariances of the auxiliary variables

$$\bar{z}_i^* = \sum_{h=1}^{n_1} \frac{z_{ih}}{n_1} \text{ and } \bar{z}_i = \sum_{h=1}^n \frac{z_{ih}}{n}$$

It is to be noted that the samples have been drawn by simple random sampling with replacement (SRSWR) scheme at both the phases. We simplify the notation by setting $s_{ii} = s_i^2, s_{ij}^* = s_i^{*2}$ and $s_{00} = s_0^2$. Now, we define the multivariate ratio estimator for σ_0^2 as

$$\hat{S}_{yd}^2 = \sum_{i=1}^k w_i \hat{r}_i s_i^{*2} + w_{k+1} s_0^2; \sum_{i=1}^{k+1} w_i = 1 \tag{3.1}$$

For $w_{k+1} = 0, \hat{S}_{yd}^2$ reduces to

$$\hat{S}_{yd1}^2 = \sum_{i=1}^k w_i \hat{r}_i s_i^{*2}, \sum_{i=1}^k w_i = 1 \tag{3.2}$$

which is double sampling version of Isaki [5] estimator \hat{S}_{ym1}^2 in (1.4). If we set $w_{k+1} = 0, \hat{S}_{yd}^2$ boils down to the usual unbiased estimator s_0^2 .

Replacing σ_i^2 by s_i^{*2} in (1.5), (1.6) and (1.7) we get double sampling versions of $\hat{S}_{ym2}^2, \hat{S}_{ym3}^2$ and \hat{S}_{ym4}^2 respectively as

$$\hat{S}_{yd2}^2 = s_0^2 \left[\frac{\left(\sum_{i=1}^k w_i s_i^{*2} \right)}{\left(\sum_{i=1}^k w_i s_i^2 \right)} \right] \tag{3.3}$$

$$\hat{S}_{yd3}^2 = \prod_{i=1}^k (\hat{r}_i s_i^{*2})^{w_i} \tag{3.4}$$

and

$$\hat{S}_{yd4}^2 = \left(\sum_{i=1}^k \frac{w_i}{\hat{r}_i s_i^{*2}} \right)^{-1} \tag{3.5}$$

where w_i 's ($i = 1, 2, \dots, k$) are suitably chosen constants such that $\sum_{i=1}^k w_i = 1$.

Now, we write the variances of \hat{S}_{yd}^2 in two cases

Case I: When the second phase sample is a subsample of first, then the variance of \hat{S}_{yd}^2 under set up (1.2), to the first degree of approximation, is given by

$$\text{Var}(\hat{S}_{yd}^2)_I = \frac{2\sigma_0^4}{(n-1)} \left[1 + \frac{(n_1 - n)}{(n_1 - 1)} (\underline{w}' \underline{D}^* \underline{w} - 2 \underline{w}' \underline{d}^*) \right] \tag{3.6}$$

which is minimized for

$$\underline{w} = \underline{D}^{*-1} \underline{d}^*, w_{k+1} = (1 - \underline{D}^{*-1} \underline{d}^*) \tag{3.7}$$

or

$$\left. \begin{aligned} w_i &= \frac{\rho^2}{[1 + (k-1)\rho^2]}; i = 1, 2, \dots, k \\ w_{k+1} &= \frac{(1 - \rho^2)}{[1 + (k-1)\rho^2]} \end{aligned} \right\} \tag{3.8}$$

Thus the minimum variance of \hat{S}_{yd}^2 is given by

$$\min. \text{Var}(\hat{S}_{yd}^2)_I = \frac{2\sigma_0^4}{(n-1)} \left[1 - \frac{(n_1 - n)}{(n_1 - 1)} \frac{k \rho^4}{\{1 + (k-1)\rho^2\}} \right] \tag{3.9}$$

which is equal to the approximate variance of the usual double sampling multivariate regression estimator

$$\hat{S}_{yrd}^2 = s_0^2 + \sum_{i=1}^k \hat{\beta}_i (s_i^{*2} - s_i^2) \tag{3.10}$$

where $\hat{\beta}_i = \frac{s_{0i}}{s_i^2}, i = 1, 2, \dots, k$

Case II: When the second phase sample is independent of the first phase, then the variance of \hat{S}_{yd}^2 under set up (1.2), to the first degree of approximation, is given by

$$\text{Var}(\hat{S}_{yd}^2)_{II} = \frac{2\sigma_0^4}{(n-1)} \left[1 - 2 \underline{w}' \underline{d}^* + \frac{(n_1 + n - 2)}{(n_1 - 1)} (\underline{w}' \underline{D}^* \underline{w}) \right] \tag{3.11}$$

which is minimized for

$$w = \frac{(n_1 - 1)}{(n_1 + n - 2)} D^{*-1} d^*, w_{k+1} = 1 - \frac{(n_1 - 1)}{(n_1 + n - 2)} D^{*-1} d^* \quad (3.12)$$

or

$$\left. \begin{aligned} w_i &= \frac{(n_1 - 1)}{(n_1 + n - 2)} \frac{\rho^2}{[1 + (k - 1)\rho^2]}, i = 1, 2, \dots, k \\ w_{k+1} &= \left[1 - \frac{(n_1 - 1)}{(n_1 + n - 2)} \frac{\rho^2}{[1 + (k - 1)\rho^2]} \right] \end{aligned} \right\} \quad (3.13)$$

Hence the resulting (minimum) variance of \hat{S}_{yd}^2 is given by

$$\min. \text{Var}(\hat{S}_{yd}^2)_{II} = \frac{2\sigma_0^4}{(n-1)} \left[1 - \frac{(n_1 - 1)}{(n_1 + n - 2)} \frac{k\rho^4}{[1 + (k - 1)\rho^2]} \right] \quad (3.14)$$

It follows from (3.9) and (3.14) that

$$\min. \text{Var}(\hat{S}_{yd}^2)_I - \min. \text{Var}(\hat{S}_{yd}^2)_{II} = \frac{2(n-1)\sigma_0^4}{(n_1-1)(n_1+n-2)} \frac{k\rho^4}{[1 + (k-1)\rho^2]} > 0 \quad (3.15)$$

which shows that the estimator \hat{S}_{yd}^2 in case II is always more efficient than in case I.

Further, in cases I and II the common minimum variance of $\hat{S}_{y_{dj}}^2$ ($j = 1$ to 4) for the set up (1.2) are respectively given by

$$\min. \text{Var}(\hat{S}_{y_{dj}}^2)_I = \frac{2\sigma_0^4}{k(n-1)} \left[(k+1)(1-\rho^2) + \left(\frac{n-1}{n_1-1} \right) \{ (k+1)\rho^2 - 1 \} \right] \quad (3.16)$$

and

$$\min. \text{Var}(\hat{S}_{y_{dj}}^2)_{II} = \frac{2\sigma_0^4}{k(n-1)} \left[(k+1)(1-\rho^2) + \left(\frac{n-1}{n_1-1} \right) \{ (k-1)\rho^2 + 1 \} \right] \quad (3.17)$$

From (3.16) and (3.17), we have

$$\min. \text{Var}(\hat{S}_{y_{dj}}^2)_I - \min. \text{Var}(\hat{S}_{y_{dj}}^2)_{II} = \frac{4(1-\rho^2)\sigma_0^4}{k(n_1-1)} > 0 \quad (3.18)$$

which follows that multivariate ratio-type estimator $\hat{S}_{y_{dj}}^2$ ($j = 1$ to 4) has smaller minimum variance in case I than that in Case II.

From (1.9), (3.9) and (3.16) we have

$$\begin{aligned} \text{Var}(s_0^2) - \min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{y_{dj}}^2) &= 2 \left[\frac{1}{n-1} - \frac{1}{n_1-1} \right] \frac{\{(k+1)\rho^2 - 1\} \sigma_0^4}{k} \\ &\geq 0 \text{ iff } |\rho| \geq (k+1)^{-1} \end{aligned} \tag{3.19}$$

and

$$\min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{y_{dj}}^2) - \min \text{Var}(\hat{S}_{y_d}^2) = 2\sigma_0^4 \left(\frac{1}{n-1} - \frac{1}{n_1-1} \right) \frac{(1-\rho^2)^2}{k\{1 + (k-1)\rho^2\}} \geq 0 \tag{3.20}$$

Thus we have the following inequality

$$\min \text{Var}(\hat{S}_{y_d}^2) \leq \min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{y_{dj}}^2) \leq \text{Var}(s_0^2) \text{ if } |\rho| \geq (k+1)^{-1} \tag{3.21}$$

Further from (1.9), (3.14) and (3.17) we have

$$\begin{aligned} \text{Var}(s_0^2) - \min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{y_{dj}}^2) &= \frac{2\sigma_0^4}{k} \left(\frac{1}{n-1} + \frac{1}{n_1-1} \right) \left[\rho^2 \left\{ 1 + \frac{(n_1-n)}{(n_1+n-2)} k \right\} - 1 \right] \\ &\geq 0 \text{ iff } |\rho| \geq \left[\frac{(n_1-n)k}{(n_1+n-2)} + 1 \right]^{-1/2} \end{aligned} \tag{3.22}$$

and

$$\begin{aligned} \min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{y_{dj}}^2) - \min \text{Var}(\hat{S}_{y_d}^2) &= \frac{2\sigma_0^4}{k} \frac{\left[(n_1-1)(1-\rho^2) + (n_1-1)\{1 + (k-1)\rho^2\} \right]^2}{(n_1-1)(n_1+n-2)\{1 + (k-1)\rho^2\}} \geq 0 \end{aligned} \tag{3.23}$$

Thus from (3.22) and (3.23) we have the following inequality

$$\min \text{Var}(\hat{S}_{y_d}^2) \leq \min_{j=1 \text{ to } 4} \text{Var}(\hat{S}_{y_{dj}}^2) \leq \text{Var}(s_0^2) \text{ if } |\rho| \geq \left[\frac{(n_1-n)k}{(n_1+n-2)} + 1 \right]^{-1/2} \tag{3.24}$$

Finally, we conclude that proposed estimator $\hat{S}_{y_d}^2$ is better than s_0^2 and $\hat{S}_{y_{dj}}^2$ ($j = 1$ to 4) in both the cases I and II.

Remark 3.1 : The efficiencies of the estimators discussed in this paper can be compared for fixed cost, following the procedure given in Sukhatme *et al.* [18] and Khan and Tripathi [7].

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